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- Collaborat ve and tact cal autonomy
- Extreme robot c mobility and manipulat on
- Verif cat on and Validat on (V&V) for autonomy
- Assured symbiosis
- Physiological, biochemical and cognit ve sensing te t c gorset nd rs ta b1 anithd

and c $\,$ n $\,$ 1 $\,$ m $\,$ vm $\,$ nvg $\,$ $\,$ $\,$ P $\,$ ia c $\,$ and $\,$ s $\,$ d